
```
module Lxz_Tools
    implicit none
    integer (kind(1)),parameter ::ikind=(kind(1))
    integer (kind(1)),parameter ::rkind=(kind(0.D0))
    real (rkind),      parameter :: Zero=0.D0,One=1.D0,Two=2.D0,Three=3.D0, &
&     Four=4.D0,Five=5.D0,Six=6.D0,Seven=7.D0,Eight=8.D0,Nine=9.D0, &
&     Ten=10.D0

    contains

    function matinv(A) result (B)
        real(rkind) ,intent (in)::A(:, :)
        !real(rkind) , allocatable::B(:, :)
        real(rkind) , pointer::B(:, :)
        integer(ikind):: N,I,J,K
        real(rkind)::D,T
        real(rkind), allocatable::IS(:),JS(:)
        N=size(A,dim=2)
        allocate(B(N,N))
        allocate(IS(N));allocate(JS(N))
        B=A
        do K=1,N
            D=0.0D0
            do I=K,N
                do J=K,N
                    if(abs(B(I,J))>D) then
                        D=abs(B(I,J))
                        IS(K)=I
                        JS(K)=J
                    end if
                end do
            end do
            do J=1,N
                T=B(K,J)
                B(K,J)=B(IS(K),J)
                B(IS(K),J)=T
            end do
            do I=1,N
                T=B(I,K)
                B(I,K)=B(I,JS(K))
                B(I,JS(K))=T
            end do
            B(K,K)=1/B(K,K)
            do J=1,N
                if(J.NE.K) then
```

```
B(K,J)=B(K,J)*B(K,K)
end if
end do
do I=1,N
  if(I.NE.K) then
    do J=1,N
      if(J.NE.K) then
        B(I,J)=B(I,J)-B(I,K)*B(K,J)
      end if
    end do
  end if
end do
do I=1,N
  if(I.NE.K) then
    B(I,K)=-B(I,K)*B(K,K)
  end if
end do
end do
do K=N,1,-1
  do J=1,N
    T=B(K,J)
    B(K,J)=B(JS(K),J)
    B(JS(K),J)=T
  end do
  do I=1,N
    T=B(I,K)
    B(I,K)=B(I,IS(K))
    B(I,IS(K))=T
  end do
end do
return
end function matinv

subroutine IntSwap(a,b)
  integer(ikind), intent(in out)::a,b
  integer(ikind)::t
  t=a;a=b;b=t
end subroutine IntSwap

subroutine RealSwap(a,b)
  real(rkind), intent(in out)::a,b
  real(rkind)::t
  t=a;a=b;b=t
end subroutine RealSwap
```

```
subroutine matprint(A,n)
    real(rkind), intent(in)::A(:, :)
    integer(ikind)::n
    integer(ikind)::n1,n2
    integer(ikind)::i,j
    character(10)::C
    n1=size(A,dim=1)
    n2=size(A,dim=2)
    C='//trim(itoc(n2))//E//trim(itoc(n))//&
    .'//trim(itoc(n-7))//)'
    do i=1,n1
        write(*,C)(A(i,j),j=1,n2)
    end do
end subroutine matprint

function matdet(B) result(det)
    real(rkind), intent(in)::B(:, :)
    real(rkind)::det
    integer(ikind)::n,i,j,k,is,js
    real(rkind),pointer::A(:, :)
    real(rkind)::f,d,q
    n=size(B,dim=1)
    allocate (A(n,n))
    A=B
    f=1.0D0;      det=1.0D0
    do k=1,n-1
        q=0.0D0
        do i=k,n
            do j=k,n
                if(abs(a(i,j)).gt.q) then
                    q=abs(a(i,j))
                    is=i
                    js=j
                end if
            end do
        end do
        if(q+1.0D0.eq.1.0D0) then
            det=0.0d0
            return
        end if
        if(is.ne.k) then
            f=-f
            do j=k,n
```

```
d=a(k,j)
a(k,j)=a(is,j)
a(is,j)=d
end do
end if
if(js.ne.k) then
f=-f
do i=k,n
d=a(i,js)
a(i,js)=a(i,k)
a(i,k)=d
end do
end if
det=det*a(k,k)
do i=k+1,n
d=a(i,k)/a(k,k)
do j=k+1,n
a(i,j)=a(i,j)-d*a(k,j)
end do
end do
end do
det=f*det*a(n,n)
deallocate (a)
return
end function matdet

function itoc(i1) result(c)
integer(ikind), intent(in)::i1
character(len=2)::c
real(rkind)::x
integer(ikind)::n,b,i,j
i=i1
x=i
c(1:2)= ' '
x=log10(x)
n=int(x)+2
do j=n-2,0,-1
b=mod(i,10**j)
b=(i-b)/(10**j)
i=i-b*(10**j)
c(n-j-1:n-j-1)=achar(iachar('0')+b)
end do
end function itoc
```

```

subroutine Gauss(GStif,GLoad,GDisp)
    real (rkind),intent (in) :: GStif(:,,:),GLoad(:)
    real (rkind),intent (out) :: GDisp(:)
    integer (ikind) :: i,j,k
    integer (ikind) :: N
    real (rkind) :: P,I1,X,Y
    real (rkind),allocatable :: A(:, :)
    N=size(GDisp,dim=1)
    allocate (A(N,N+1))
    A(1:N,1:N)=GStif(1:N,1:N)
    A(1:N,N+1)=GLoad(1:N)
    DO j=1,N
        P=0.0D0
        DO k=j,N
            IF(ABS(A(k,j)).LE.P) cycle
            P=ABS(A(k,j)))
            I1=k
        end do
        IF(P.GE.1E-15)GO TO 230
        WRITE(22,'(A)') 'NO UNIQUE SOLUTION'
        RETURN
    230 IF(I1.EQ.j)GO TO 280
        DO 270 K=J,N+1
            X=A(J,K)
            A(J,K)=A(I1,K)
    270     A(I1,K)=X
    280     Y=1.D0/A(J,J)
        DO 310 K=J,N+1
            A(J,K)=Y*A(J,K)
    310     DO 380 I=1,N
                IF(I.EQ.J)GO TO 380
                Y=-A(I,J)
    380     DO 370 K=J,N+1
                    A(I,K)=A(I,K)+Y*A(J,K)
    370     CONTINUE
    380 end do

    GDisp=A(1:N,N+1)
    end subroutine Gauss

end module Lxz_Tools

```

```

module TypDef

```

```

use Lxz_Tools
implicit none

integer(ikind) :: NNode, NSolid, NShell !节点数量，实体单元数量，壳单元数量
integer(ikind) :: NMaterial, NRealConstant !材料数量，实参数数量
integer(ikind) :: NGlbDOF !整体自由度总数

type Typ_Node !定义节点类型
    real(rkind) :: coord(3) !节点坐标
    integer(ikind) :: EElTyp !从属单元类型 1 - solid 单元, 2 - shell 单元
    integer(ikind) :: GDOF(6) !整体自由度编码 如果不从属与 shell，则
GDOF(4:6)=0
    real(rkind) :: disp(6) !节点位移
end type typ_Node

type Typ_Material !定义材料
    real(rkind) :: E !弹性模量
    real(rkind) :: mu !泊松比
end type Typ_Material

type Typ_RealConstant !定义实参数
    real(rkind) :: Thickness !板单元厚度
end type Typ_RealConstant

!=====
type Typ_Plate !定义板单元
    real(rkind) :: NCoord(2,4) !节点的局部坐标
    integer(ikind) :: NodeNo(4) !节点编号
    real(rkind) :: t !板厚度
    real(rkind) :: E,MU !弹性模量
    real(rkind) :: D(5,5) ![D]矩阵
    real(rkind) :: B(5,12) ![B]矩阵
    real(rkind) :: EK(12,12) ![EK]单元刚度矩阵
    real(rkind) :: S(5,12) ![S]单元应力矩阵
    real(rkind) :: GaussPoint(2,4) !高斯积分点坐标
    real(rkind) :: N(4,4) !形函数矩阵，四个高斯积分点
    real(rkind) :: dN(4,2,4) !形函数矩阵局部坐标系下求导，四个高斯积分点 !
    real(rkind) :: d0(4,2,4) !形函数矩阵整体坐标系下求导，四个高斯积分点 !
    real(rkind) :: Jacobi(2,2,4) !Jacobi 矩阵，四个高斯积分点 !
    real(rkind) :: InvJ(2,2,4) !Jacobi 矩阵的逆矩阵
    real(rkind) :: SJ(4) !|J| , Jacobi 矩阵行列式的值，四个高斯积分点 !
    !
end type Typ_Plate

```

```
!=====
type Typ_Membrance !定义膜单元
    real(rkind) :: NCoord(2,4) !节点的局部坐标
    integer(ikind) :: NodeNo(4) !节点编号
    real(rkind)::EK(8,8),B(3,8),D(3,3),J(2,2)
    real(rkind)::E,MU,t
    !.....
end type Typ_Membrance

type Typ_Solid !定义实体单元
    integer(ikind) :: NodeNo(8) !节点编号
    integer(ikind) :: MatNo !材料号
    real(rkind) :: E,MU
    real(rkind) :: EK(24,24)
    !.....
end type Typ_Solid

type Typ_Shell !定义壳单元
    integer(ikind) :: NodeNo(4) !节点坐标
    integer(ikind) :: MatNo !材料号
    integer(ikind) :: RealNo !实参数号
    real(rkind) :: E,MU,t
    type(typ_Plate) :: S_Plate(1) !Shell 里面的板部分
    type(typ_Membrance) :: S_Membrance(1) !shell 里面膜部分
    real(rkind) :: TransMatrix(24,24) !坐标转换矩阵
    real(rkind) :: EK(24,24) !刚度矩阵
    !.....
    real(rkind) :: NCoord(2,4) !节点的局部坐标
end type Typ_Shell

type Typ_Load
    integer(ikind) :: NodeNo
    integer(ikind) :: DOF
    real(rkind) :: Value
end type Typ_Load

type Typ_Support
    integer(ikind) :: NodeNo
    integer(ikind) :: DOF
end type Typ_Support
```

contains

```
subroutine TypDef_DOFCount(Node, Solid, Shell) !单元自由度编码子程序
```

```
    type(Typ_Node) :: Node(:)
```

```
    type(Typ_Solid) :: Solid(:)
```

```
    type(Typ_Shell) :: Shell(:)
```

```
    integer(ikind) :: i,j,k !循环变量
```

```
    integer(ikind) :: TempDOF !总体自由度的工作变量
```

```
Node(:)%EleTyp=1 !假设所有节点都是只从属于实体单元
```

```
do i=1, NNode
```

```
    do j=1, NShell
```

```
        do k=1,4
```

```
            if(Shell(j)%NodeNo(k)==i) then !如果壳单元 j 的第 k 个节点和 i
```

```
节点相同
```

```
            Node(i)%EleTyp=2; ! 那么节点 i 从属于壳单元
```

```
        end if
```

```
    end do ! for k
```

```
end do ! for j
```

```
end do ! for i
```

```
!以下开始计算各个单元的自由度数量和总体自由度数量
```

```
TempDOF=0 !清空变量
```

```
do i=1, NNode
```

```
    if(Node(i)%EleTyp==1) then !如果节点只从属与实体单元
```

```
        Node(i)%GDOF(1)=TempDOF+1; Node(i)%GDOF(2)=TempDOF+2;
```

```
        Node(i)%GDOF(3)=TempDOF+3;
```

```
        Node(i)%GDOF(4:6)=0;
```

```
        TempDOF=TempDOF+3; !总体自由度增加了 3 个
```

```
    end if
```

```
    if(Node(i)%EleTyp==2) then !如果节点从属与壳单元
```

```
        Node(i)%GDOF(1)=TempDOF+1; Node(i)%GDOF(2)=TempDOF+2;
```

```
        Node(i)%GDOF(3)=TempDOF+3;
```

```
        Node(i)%GDOF(4)=TempDOF+4; Node(i)%GDOF(5)=TempDOF+5;
```

```
        Node(i)%GDOF(6)=TempDOF+6;
```

```
        TempDOF=TempDOF+6; !总体自由度增加了 6 个
```

```
    end if
```

```
end do !for i
```

```
NGibDOF=TempDOF
```

```
return
```

```
end subroutine TypDef_DOFCount
```

```

end module TypDef

module SolidDef
    use Lxz_Tools
    use TypDef

    contains
! *****
!      得到形函数
    SUBROUTINE Solid_SHAP3(U,V,W,XQ,XJAC,XVJ,DETJ,SHP)
!
! *****
! -----
! COMPUTE SHAPE FUNCTION AND DERIVATIVES FOR 3D 8-NODE ELEMENT
! -----
IMPLICIT REAL*8(A-H,O-Z)
DIMENSION SHP(3,8),XQ(3,8),XJAC(3,3),XVJ(3,3),&
           UI(8),VI(8),WI(8),IT2(3),IT3(3)
DATA UI/-0.5D0,0.5D0,0.5D0,-0.5D0,-0.5D0,0.5D0,0.5D0,-0.5D0/
DATA VI/-0.5D0,-0.5D0,0.5D0,0.5D0,-0.5D0,-0.5D0,0.5D0,0.5D0/
DATA WI/-0.5D0,-0.5D0,-0.5D0,-0.5D0,0.5D0,0.5D0,0.5D0,0.5D0/
DATA IT2/2,3,1/, IT3/3,1,2/
!
! 变量说明
! U,V,W 为高斯积分点坐标
! SHP(1:3,:) 先存放 Ni 对 U , V , W 取偏导 , 后存放对 X , Y , Z 的偏导
! SHP(4,:) 为 Ni
! XQ(:,8) 为节点坐标
! XJAC 为雅可比矩阵 , XVJ 为雅可比逆矩阵
! 求 Ni 及 Ni 对 U,V,W 的偏导

DO 10 I=1,8
    SHP(4,I)=(0.5D0+UI(I)*U)*(0.5D0+VI(I)*V)*(0.5D0+WI(I)*W)
    SHP(1,I)=UI(I)*(0.5D0+VI(I)*V)*(0.5D0+WI(I)*W)
    SHP(2,I)=VI(I)*(0.5D0+UI(I)*U)*(0.5D0+WI(I)*W)
    SHP(3,I)=WI(I)*(0.5D0+UI(I)*U)*(0.5D0+VI(I)*V)
10 CONTINUE
!
! 求雅可比矩阵
DO 20 I=1,3
    DO 20 J=1,3
        XJAC(I,J)=0.0D0
        DO 20 K=1,8
            20 XJAC(I,J)=XJAC(I,J)+XQ(I,K)*SHP(J,K)
!
! 求雅可比矩阵行列式
    WJ1=XJAC(1,1)*XJAC(2,2)*XJAC(3,3)+XJAC(3,1)*XJAC(1,2)*&

```

```

XJAC(2,3)+XJAC(1,3)*XJAC(2,1)*XJAC(3,2)
WJ2=XJAC(1,3)*XJAC(3,1)*XJAC(2,2)+XJAC(1,2)*XJAC(2,1)*&
    XJAC(3,3)+XJAC(2,3)*XJAC(3,2)*XJAC(1,1)
DETJ=WJ1-WJ2
!      得到雅可比逆矩阵
DO 25 I=1,3
DO 25 J=1,3
M2=IT2(I)
M3=IT3(I)
N2=IT2(J)
N3=IT3(J)
25 XVJ(I,J)=(XJAC(M2,N2)*XJAC(M3,N3)-XJAC(M2,N3)&
    *XJAC(M3,N2))/DETJ
!      W1, W2, W3 为临时变量 , 存放 Ni 对 X , Y , Z 的偏导
DO 30 I=1,8
W1=0.0D0
W2=0.0D0
W3=0.0D0
DO 35 K=1,3
W1=W1+XVJ(1,K)*SHP(K,I)
W2=W2+XVJ(2,K)*SHP(K,I)
35 W3=W3+XVJ(3,K)*SHP(K,I)
!      把 Ni 对 X,Y,Z, 的偏导存入 SHP
SHP(1,I)=W1
SHP(2,I)=W2
SHP(3,I)=W3
30 CONTINUE
RETURN
END subroutine
!
!
!      得到矩阵 B(6,24)
Subroutine Solid_GETB(B,SHP)
implicit real*8(A-H,O-Z)
dimension B(6,24),SHP(3,8)
integer i,j
do 10 i=1,8
    j=(i-1)*3+1
    b(1,j)=SHP(1,I)
    B(1,J+1)=0.0d0
    B(1,J+2)=0.0D0
    B(2,J)=0.0d0
10

```

```
B(2,J+1)=SHP(2,I)
B(2,J+2)=0.0D0

B(3,J)=0.0d0
B(3,J+1)=0.0d0
B(3,J+2)=SHP(3,I)

B(4,J)=SHP(2,I)
B(4,J+1)=SHP(1,I)
B(4,J+2)=0.0D0

B(5,J)=0.0d0
B(5,J+1)=SHP(3,I)
B(5,J+2)=SHP(2,I)

B(6,J)=SHP(3,I)
B(6,J+1)=0.0d0
B(6,J+2)=SHP(1,I)

10 continue
      return
      end subroutine
! ****
! ****
! **** subroutine Solid_MutBAB(M,N,A,B,C)
! ****
! ****
! ****
! ****
! **** implicit real*8 (A-H,O-Z)
      Dimension A(N,N),C(M,M),B(N,M),AB(N,M)
!
      do 12 I=1,N
      do 12 J=1,M
      W1=0.0d0
      DO 14 K=1,N
14    W1=W1+A(I,K)*B(K,J)
12    AB(I,J)=W1
      DO 16 I=1,M
      Do 16 J=1,M
      W2=0.0D0
      Do 18 K=1,N
18    W2=W2+B(K,I)*AB(K,J)
16    C(I,J)=W2
      return
      end subroutine
```

```
!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
```

```
subroutine Solid_GetDB(DB,D,B)
    implicit none
    real*8 DB(6,24),D(8,6,6),B(6,24)
    integer i,j,k,l
    do 5 i=1,6
    do 5 j=1,24
5      DB(I,J)=0.0d0
    Do 10 l=1,6
        do 20 J=1,24
            L=(J-1)/3+1
            Do 30 K=1,6
                DB(I,J)=DB(I,J)+D(L,I,K)*B(K,J)
30          continue
20          continue
10          continue
        return
    end subroutine
```

```
!*****
```

```
subroutine Solid_GetBDB(BDB,B,D)
    implicit none
    real*8 BDB(24,24),B(6,24),D(6,6)
    BDB=Matmul(matmul(transpose(B),D),B)
    return
end subroutine
```

```
!*****
```

```
subroutine Solid_GetD(D,E,EMU)
    implicit real*8(A-H,O-Z)
    Dimension D(6,6)
    integer I,J
    D=0.0d0
    Temp=E*(1-EMU)/((1+EMU)*(1-2*EMU))
    D(1,1)=1
    D(2,2)=1
    D(3,3)=1
    D(1,2)=EMU/(1-EMU)
    D(2,1)=D(1,2)
    D(1,3)=EMU/(1-EMU)
    D(3,1)=D(1,3)
```

```
D(2,3)=EMU/(1-EMU)
D(3,2)=D(2,3)
D(4,4)=(1-2*EMU)/(2*(1-EMU))
D(5,5)=D(4,4)
D(6,6)=D(4,4)
D=temp*D
return
end subroutine
```

```
!*****
```

```
subroutine Solid_GetEK(EK,XQ,E0,EMU0)
implicit none
real*8 XQ(3,8),XJAC(3,3),XVJ(3,3),SHP(3,8)
real*8 B(6,24),DB(6,24),BDB(24,24),D(6,6),DISP(24)
real*8 E0,EMU0
real*8 EK(24,24),PLASTICD(8,6,6)
real*8 U,V,W,H1,H2,H3,DETJ
real*8 I,J,K,II,JJ,KK
integer RETVAL

DO 5 II=1,24
DO 5 JJ=1,24
5   EK(II,JJ)=0.0d0
DO 10 I=1,3
IF(I.EQ.1) U=0.77459669241483d0
if(I.eq.1) H1=0.55555555555555d0
if(I.eq.2) U=0.0d0
if(I.eq.2) H1=0.8888888888889d0
if(I.eq.3) U=-0.77459669241483d0
if(I.eq.3) H1=0.55555555555555d0

do 20 J=1,3
IF(J.EQ.1) V=0.77459669241483d0
if(J.eq.1) H2=0.55555555555555d0
if(J.eq.2) V=0.0d0
if(J.eq.2) H2=0.8888888888889d0
if(J.eq.3) V=-0.77459669241483d0
if(J.eq.3) H2=0.55555555555555d0

do 30 K=1,3
IF(K.EQ.1) W=0.77459669241483d0
if(K.eq.1) H3=0.55555555555555d0
if(K.eq.2) W=0.0d0
```

```
    if(K.eq.2) H3=0.8888888888889d0
    if(K.eq.3) W=-0.77459669241483d0
    if(K.eq.3) H3=0.55555555555555d0

    call Solid_SHAP3(U,V,W,XQ,XJAC,XVJ,DETJ,SHP)
    call Solid_GetB(B,SHP)
    call Solid_GetD(D,E0,EMU0)
    call Solid_GetBDB(BDB,B,D)

    do 100 II=1,24
    do 100 JJ=1,24
100     EK(II,JJ)=EK(II,JJ)+H1*H2*H3*BDB(II,JJ)*DETJ
30     continue
20     continue
10     continue
        return
end subroutine

subroutine Solid_EK(Solid,Node)
    type(typ_Solid) :: Solid(:)
    type(Typ_Node)  :: Node(:)
    integer(ikind)   :: i,j,k
    real(rkind)      :: XQ(3,8)
    do i=1,size(Solid)
        do j=1,8
            XQ(:,j)=Node(Solid(i)%NodeNo(j))%Coord
        end do !for j
        call Solid_GetEK(Solid(i)%EK,XQ,Solid(i)%E,Solid(i)%MU)
    end do !for i
    return
end subroutine
end module

program Main
    use Ixz_Tools
    use TypDef
    use SolidDef
    use IMSL
    implicit none

    type(typ_Solid),pointer :: Solid(:)
    type(Typ_Node), pointer :: Node(:)

    real(rkind),pointer :: GK(:,:,), GF(:, ), GD(:)
```

```

real(rkind) :: temp
integer(ikind) :: NElem, NSupport, NLoad;
integer(ikind) :: i,j,k,l,m

open(55, file='datain.txt')
read(55,*)
read(55,*) NNode, NElem, NSupport, NLoad

allocate(Node(NNode))
allocate(Solid(NElem))
allocate(GK(3*NNode,3*NNode))
allocate(GF(3*NNode))
allocate(GD(3*NNode))

read(55,*)
do i=1,size(Node)
    read(55,*) j, Node(i)%Coord(1:3)
end do
read(55,*)
do i=1,size(Solid)
    read(55,*) j, solid(i)%NodeNo
    ! do k=1,4
    !     Plate(i)%NCoord(:,k)=Node(Plate(i)%NodeNo(k))%Coord(1:2)
    ! end do
end do
solid(:)%E=210.0d0; solid(:)%MU=0.3d0;
call Solid_EK(Solid,Node)
GK=0.0d0; GF=0.0d0; GD=0.0d0
do i=1,size(Solid)
    do j=1,8
        do k=1,8
            do l=1,3
                do m=1,3
                    GK((Solid(i)%NodeNo(j)-1)*3+l,(Solid(i)%NodeNo(k)-1)*3+m)=&
                    GK((Solid(i)%NodeNo(j)-1)*3+l,(Solid(i)%NodeNo(k)-1)*3+m)+&
                    Solid(i)%Ek((j-1)*3+l,(k-1)*3+m)

                end do ! for m
            end do ! for l
        end do ! for k
    end do ! for j
end do ! for i

GF(58)=1000;

```

```
temp=maxval(GK)
GK(1,1)=GK(1,1)+1.0D5*temp;
GK(2,2)=GK(2,2)+1.0D5*temp;
GK(3,3)=GK(3,3)+1.0D5*temp;
GK(4,4)=GK(4,4)+1.0D5*temp;
GK(5,5)=GK(5,5)+1.0D5*temp;
GK(6,6)=GK(6,6)+1.0D5*temp;
GK(16,16)=GK(16,16)+1.0D5*temp;
GK(17,17)=GK(17,17)+1.0D5*temp;
GK(18,18)=GK(18,18)+1.0D5*temp;
call DLSARG (size(GF), GK, size(GF), GF, 1, GD)
! open (77,file='dataout1.txt')
!     write(77,*) i,shell(1)%NCoord
! close(77)

open (77,file='dataout.txt')
do i=1,NNode
    !write(77,*) i
    write(77,'(13,3E12.4)') i, GD((i-1)*3+1),GD((i-1)*3+2),GD((i-1)*3+3)
end do
close(77)
stop
stop
end program
```